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TITLE*A Method and Apparatus for Controlling the
Operation of a Flexible Cross-Connect System*

This application claims the priority of Provisional Application
10 60/125,526 which was filed on March 22, 1999. This application
is also related to Application 09/274,078 which was also filed on
March 22, 1999 (the same day as the provisional application).
Applications 60/125,526 and 09/274,078 are herein incorporated by
reference but are not admitted to be prior art.

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Background of the Invention

Telecommunications (telecom) systems are carrying increasing amounts of information, both in long distance networks as well as in metropolitan and local area networks. At present, data traffic is growing much faster than voice traffic, and includes high bandwidth video signals. In addition to the requirement for equipment to carry increasing amounts of telecom traffic there is a need to bring this information from the long distance networks to businesses and to locations where it can be distributed to residences over access networks.

The equipment which has been developed to carry large amounts of telecom traffic includes fiber optic transport equipment which can carry high speed telecom traffic. The data rates on fiber optic systems can range from millions of bits per second (Mb/s) to billions of bits per second (Gb/s). In addition, multiple wavelengths of light can be carried on an optical fiber using Wavelength Division Multiplexing (WDM) techniques.

The ability to carry large amounts of telecom traffic on an optical fiber solves the long-distance point-to-point transport problem, but does not address the issue of how to add and remove traffic from the high-speed data stream. Equipment for adding

5 and removing traffic has been developed and is referred to as
"add-drop" multiplexers (ADMs).

Traditional designs for ADMs are based on the use of multiple interface cards which receive high-speed data streams, create a time division multiplex signal containing the multiple 10 data streams, and route the time division multiplex signal to a cross-connect unit which can disassemble the data streams, remove or insert particular data streams, and send the signal to another interface card for transmission back into the networks. By aggregating the multiple data streams into a time division 15 multiplexed data signal, the data rate of the time division multiplexed signal is by definition several times the rate of the maximum data rate supported by the interface cards. Traditional ADMs have proven adequate for interface data rates in the range of 155 Mb/s to 622 Mb/s.

However, optical signals of at least 2.4 Gb/s have become standard, and traditional ADMs do not work for these high-speed optical signals. That is, numerous problems arise due to the timing associated with the multiplexing and transmission of the high-speed signals between the interface cards and the cross-connect unit. Thus, there is a need for cross-connect equipment which can support multiple high speed data streams (i.e., at least 2.4 Gb/s).

Standardized interfaces and transmission hierarchies for telecom signals have been developed and include Pleisochronous 30 Digital Hierarchy (PDH), Synchronous Digital Hierarchy (SDH) standards, and Synchronous Optical Network (SONET). In addition to these telecom transport standards, standards have been developed for interconnecting businesses and computers within businesses. These Metropolitan and Local Area Network (MAN/LAN) 35 standards include Ethernet, Gigabit Ethernet, Frame Relay, and Fiber Distributed Data Interface (FDDI). Other standards, such

5 as Integrated Services Digital Network (ISDN) and Asynchronous Transfer Mode (ATM) have been developed for use at both levels.

Individual pieces of equipment can be purchased to support telecom or MAN/LAN standards. However, these devices generally either connect data streams using a signal protocol or convert
10 entire data streams from one protocol to another. Thus, there is a need for a device which can establish interconnectivity between interfaces at the MAN/LAN level, while providing cross-connection to interfaces at the telecom network level.

Multiple interfaces are presently supported in cross-connect equipment using different interface cards. High-speed interface cards must be inserted into particular slots in order to insure that the high-speed signals can be transported to and from the cross-connect unit and to and from the high-speed interface cards. It would be desirable to have a cross-connect system in which all cards can support high-speed optical signals of at least 2.4 Gb/s, regardless of the card slot they are located in. Moreover, it would also be useful to have a system which would support routing, bridging, and concentration functions within MANs/LANs, as well as permitting access to telecom networks.
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For the foregoing reasons, there is a need for a flexible cross-connect apparatus that includes a data plane and can support multiple high-speed optical interfaces in any card slot. Furthermore, the flexible cross-connect apparatus can establish connectivity between data cards and the telecom networks.
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Summary of the Invention

The present invention discloses a method and apparatus for cross-connecting high-speed telecommunications signals at a flexible cross-connect system. A method and apparatus for controlling communications between each of the cards located within the flexible cross-connect system is also disclosed. The method and apparatus also detect and report failures within the
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5 system, receive and validate software upgrades from external sources, maintain synchronization within the system, and monitor communication maps for the system.

According to one embodiment, a method for controlling the operation of a flexible cross-connect system that includes a
10 control unit, a plurality of interface cards, a cross-connect unit and a backplane is disclosed. The method includes managing provisioning data for the entire flexible cross-connect system, managing the communications between the control unit and all subordinate cards (plurality of interface cards and the cross-
15 connect unit), and maintaining synchronization within the flexible cross-connect system.

According to one embodiment, a computer program embodied on a computer readable medium for controlling the operation of a flexible cross-connect system is disclosed. The computer program includes a code segment for providing internal interfaces between all code segments of the computer program, a code segment for managing provisioning data for the entire flexible cross-connect system, a code segment for managing the communications between the control unit and all subordinate cards, and a code segment for maintaining synchronization within the flexible cross-connect system.

According to one embodiment, a method for downloading or upgrading software for a flexible cross-connect system is disclosed. The method includes establishing communications
30 between the flexible cross-connect system and an external management system, receiving the software download from the external management system, verifying the integrity of the software download, and storing the software download.

According to one embodiment, a computer program for
35 downloading or upgrading software for a flexible cross-connect system is disclosed. The computer program includes a code segment for establishing communications between the flexible

5 cross-connect system and an external management system; a code segment for receiving the software download from the external management system; a code segment for verifying the integrity of the software download; and a code segment for storing the software download.

10 According to one embodiment, a method for maintaining a connection map for a flexible cross-connect system, wherein the flexible cross-connect system is a single node in at least one network and the connection map tracks a configuration for the at least one network is disclosed. The method includes storing a listing of all nodes of each network that the flexible cross-
15 connect system is a part of; detecting when a change (i.e., switching to or from a protection channel) in status for the flexible cross-connect system occurs; reporting the change to all of the nodes of each of the networks that the flexible cross-
20 connect system is a part of; and updating the connection map to indicate the change in status of the flexible cross-connect system.

According to one embodiment, a computer program for maintaining a connection map for a flexible cross-connect system is disclosed. The computer program includes a code segment for storing a listing of all nodes of each network that the flexible cross-connect system is a part of; a code segment for detecting when a change in status for the flexible cross-connect system occurs; a code segment for reporting the change to all of the nodes of each of the networks that the flexible cross-
30 connect system is a part of; and a code segment for updating the connection map to indicate the change in status of the flexible cross-connect system.

According to one embodiment, a method for monitoring and maintaining the status of, and controlling the communications to, each subordinate card within a flexible cross-connect system is disclosed. The method includes monitoring an operational state

5 for each subordinate card and each communications link within the flexible cross-connect system; determining when the operational state for any of the subordinate cards or the communications links indicates that maintenance is required; and reporting that maintenance is required for the determined subordinate card or
10 the determined communications link.

According to one embodiment, a computer program for monitoring and maintaining the status of, and controlling the communications to, each subordinate card within a flexible cross-connect system is disclosed. The computer program includes a
15 code segment for monitoring an operational state for each subordinate card and each communications link within the flexible cross-connect system; a code segment for determining when the operational state for any of the subordinate cards or the communications links indicates that maintenance is required; and a code segment for reporting that maintenance is required for the determined subordinate card or the determined communications link.

These and other features and objects of the invention will be more fully understood from the following detailed description of the preferred embodiments which should be read in light of the accompanying drawings.

Brief Description of the Drawings

The accompanying drawings, which are incorporated in and
30 form a part of the specification, illustrate the embodiments of the present invention and, together with the description serve to explain the principles of the invention.

In the drawings:

FIG. 1 illustrates a block diagram of the flexible cross-
35 connect system, according to one embodiment;

FIG. 2 illustrates a functional diagram of the flexible cross-connect system, according to one embodiment;

5 FIG. 3 illustrates communication channels between elements of the flexible cross-connect system, according to one embodiment;

FIG. 4 illustrates a functional diagram of the software, according to one embodiment;

10 FIG. 5 illustrates the interfaces for the processors of the system, according to one embodiment;

FIG. 6 illustrates the software supporting each of the interfaces of FIG. 5, according to one embodiment;

15 FIG. 7 illustrates the flexible cross-connect system within multiple networks, according to one embodiment; and

FIG. 8 illustrates the software architecture of the control system, according to one embodiment.

**Detailed Description
of the Preferred Embodiments**

In describing a preferred embodiment of the invention illustrated in the drawings, specific terminology will be used for the sake of clarity. However, the invention is not intended to be limited to the specific terms so selected, and it is to be understood that each specific term includes all technical equivalents which operate in a similar manner to accomplish a similar purpose.

With reference to the drawings, in general, and FIGS. 1 through 8 in particular, the apparatus and method of the present invention are disclosed.

The present invention supports numerous telecommunications (telecom) and networking standards, including the following which are incorporated herein by reference:

- Bellcore Standard GR-253 CORE, Synchronous Optical Network (SONET) Transport Systems: Common Generic Criteria, Issue 2, December 1995;

- 5 • Bellcore Standard GR-1230 CORE, SONET Bi-directional Line-Switched Ring Equipment Generic Criteria, Issue 3A, December 1996;
- 10 • Bellcore Standard GR-1400 CORE, SONET Uni-directional Line-Switched Ring Equipment Generic Criteria;
- 15 • Bellcore TR-NWT-000496, SONET Add-Drop Multiplex Equipment (SONET ADM) Generic Criteria, Issue 3, May 1992;
- 20 • Bellcore Transport System Generic Requirements FR-440, Issue No. 98, September 1998; IEEE/ANSI 802.3 Ethernet LAN specification; and
- 25 • Networking Standards, by William Stallings, published by Addison-Wesley Publishing Company (New York, 1993).

30 FIG. 1 illustrates a block diagram of a flexible cross-connect system 10 capable of routing traffic across two high-bandwidth planes. The flexible cross-connect system 10 includes a telecom plane 100, such as a SONET plane, and a data plane 110. The telecom plane 100 includes telecom plane network interface subsystems 130, and the data plane 110 includes data plane network interface subsystems 140. A centralized fully non-blocking cross-connect unit (XC) 120 is located in the telecom plane 100, which interfaces with the telecom plane network interface subsystems 130 and the data plane network interface subsystems 140.

35 Standardized telecom traffic, such as SONET, Synchronous Digital Hierarchy (SDH) and Pleisochronous Digital Hierarchy (PDH), enters the system through the telecom plane network interface subsystems 130, such as electrical or optical interface subsystems. The telecom traffic is transmitted from the telecom plane network interface subsystems 130 over point-to-point connections 150 to the XC 120. The XC 120 processes the telecom traffic and then transmits the processed data back to a telecom network, such as a Wide Area Network (WAN), or transmits the

5 processed data to a data network, such as a Metropolitan or Local Area Network (MAN/LAN). The processed data is transmitted to the telecom network via the telecom plane network subsystem(s) 130, and to the data network via the data plane network interface subsystem(s) 140.

10 Standardized telecom signals include, but are not limited to, DS-1 (1.5 Mb/s), B-ISDN (1.5Mb/s) DS-2 (6.3Mb/s), DS-3 (44.7 Mb/s), CEPT-1 (2.048 Mb/s), CEPT-2 (8.45 Mb/s), CEPT-3 (34.37 Mb/s), CEPT-4 (139.3 Mb/s), electrical STS-1 and its multiples, electrical STM-1 and its multiples, and optical OC-1 and its
15 multiples. Other standardized and non-standardized transmission signal formats can be supported and are understood by those skilled in the art.

20 Standardized data traffic, such as Ethernet, enters the system through the data plane network interface subsystems 140, such as electrical or optical interface subsystems. The data plane network interface subsystems 140 communicate with the XC 120 via point-to point connections 150. The data plane 110 also allows for communications between data plane network interface subsystems 140 via point-to-point connectors 160. Thus, the data traffic can be processed by multiple data plane interface subsystems 140 before being transmitted to the XC 120 or back to the data network. As with the telecom traffic, the XC 120 processes the data traffic and transmits the processed data to a telecom network or a data network.

25 Standardized data signals include, but are not limited to, packet data transport formats such as Frame Relay, Asynchronous Transfer Mode (ATM), and Integrated Services Digital Network (ISDN); and MAN/LAN formats such as Ethernet, Fiber Distributed Data Interface (FDDI), and Token Ring. The interfaces supported by the data plane network interface subsystems 140 include electrical Ethernet interfaces such as 10BaseT and 100BaseT, as
30 well as optical interfaces such as 1000BaseT and Gigabit

5 Ethernet. Other data-centric interfaces can be used and are understood by those skilled in the art.

In one embodiment, the point-to-point connections 150 between the XC 120 and the telecom plane network interface subsystems 130 or between the XC 120 and the data plane network 10 interface subsystems 140 are all in a single specified format. For example, in a preferred embodiment, all the point-to-point connections 150 are high-speed connections realized as Synchronous Transfer Signal (STS)-192 formatted signals. The STS-192 signals are transported on a multi-trace electrical bus 15 formed on a high-speed backplane.

In an alternative embodiment, as illustrated in FIG. 2, specific network interface subsystems are designated as high-speed interface subsystems 200 and others are designated as low-speed interface subsystems 220 having corresponding high-speed connections 230 and low-speed connections 240 to the XC 120. For example, the low-speed interconnections 240 may operate at the STS-48 rate of 2.488 Gb/s, while the high-speed interconnections 230 may operate at the STS-192 rate of 9.953 Gb/s.

The high speed network interface subsystems 200 may be realized as printed circuit boards containing active and passive electrical and optical components, and may contain multiple network interfaces 202 operating at the same or different speeds. The low speed network interface subsystems 220 may also be realized as printed circuit boards with active and passive 30 electrical and optical components, and can contain multiple network interfaces 202 operating at the same or different speeds. As an example, a low speed network interface subsystem 220 can be realized as a DS-1 interface board supporting 14 DS-1 interfaces. Alternatively, a low speed network interface subsystem 220 can be 35 realized as an Ethernet board supporting multiple Ethernet interfaces.

5 As illustrated in FIG. 3, the XC 120 has direct point-to-point connections 150 with each interface subsystem 301, 302, 303, 304, 309, 311, 312, 313, 314, 319. Each of the interface subsystems 301-304, 309, 311-314, and 319 represent an interface card which is either of the class of cards which are telecom
10 plane network interface subsystems 130 (high-speed) or which are data plane network interface subsystems 140 (low-speed). There are multiple point-to-point System Communication Links (SCLs) 352 between a centralized Timing, Control, and Communications subsystem (TCC) 300 and each of the interface subsystems 301-304, 309, 311-314, and 319. The TCC 300 is also directly connected to the XC 120 via a TCC to XC communication bus 360. In a preferred embodiment, the system has a redundant XC 325 and a redundant TCC 305.

The XC 120 provides the switching fabric for the system. As the central switching element for the system, the XC 120 features low latency and fast switching to establish connections and perform time division switching at an STS-1 level between the XC 120 and the telecom network interface subsystem 130 and between the XC 120 and the data plane network interface subsystem 140.

The TCC 300 performs system initialization, provisioning, alarm reporting, maintenance, diagnostics, Internet Protocol (IP) address detection/resolution, SONET Data Communications Channel (DCC) termination, and system fault detection for the system.

30 The TCC 300 also ensures that the system maintains Bellcore timing requirements. These functions can be performed by a processor which executes a set of computer instructions stored on a computer readable memory.

FIG. 4 illustrates a functional diagram of the software 400 of the flexible cross-connect system 10. The software 400 can be divided into two functional subsystems, a Network Management Interface System (NMIS) 410 and a Control System (CS) 420. The NMIS 410 provides the interface between and communicates with

5 external machines, such as a PC or workstation. The external machine may either be an Element Management System (EMS) 430 or an off-node Network Management System (NMS) 440. A Java and C++ based Corba system is preferably utilized to provide a computing environment between the NMIS 410 and the EMS 430 or the NMS 440.

10 The NMIS 410 also performs validation of all commands received from the EMS 430 or the NMS 440, and transmits the validated inputs to the CS 420. The NMIS 410 receives all information related to the status of the flexible cross-connect system 10 from the CS 420. In a preferred embodiment, the NMIS 410 can

15 transmit the data to a Java application in a browser, the NMS 440 for presentation to a user, or to the OMS. In one embodiment, the NMIS 410 is written using an object oriented software language, and preferably is written using C++. In a preferred embodiment, the NMIS 410 is also written in Java, to the extent that the NMIS 410 can transmit Java commands to the EMS 430 or the NMS 440.

In a preferred embodiment, the EMS 430 and the NMS 440 will act as a Java Virtual Machine (JVM). That is, each of the devices communicating with the flexible cross-connect system 10 will be able to receive the Java commands transmitted from the NMIS 410 as if it were a Java processor. Stated alternatively, the EMS 430 and the NMS 440 act a web browser and receive Java commands from the NMIS 410 which is acting as a web server.

In one embodiment, as illustrated in Fig. 5, the software 30 400 is hosted on two separate processors, with one processor being the master processor and the other processor being a slave. The master processor will handle communications with the EMS 430 or the NMS 440, and control the overall operation of the flexible cross-connect system 10. The master processor will thus be known 35 as the Control Processor (CP) 500. In a preferred embodiment, the CP 500 is an MPC860 processor or the like. The slave processor will handle Data Communications Channels (DCCs) to

5 other flexible cross-connect systems 10 and be used for the additional ports. The slave processor will thus be known as the DCC processor (DCCP) 550. In a preferred embodiment, the DCCP 550 is an MPC860MH processor or the like.

Fig. 5 illustrates the interfaces of each of the processors 10 (the CP 500 and the DCCP 550) running the software 400. In one embodiment, the CP 500 has two Serial Management Controllers (SMCs) 502, 504 and four Serial Communications Controllers (SCCs) 506, 508, 510, 512, and the DCCP 550 has one SMC 552 and four SCCs 554, 556, 558, 560.

15 Each processor, the CP 500 and the DCCP 550, will host remote monitoring software which tracks the status of the system so as to aid in the debugging process. Access to the status/debug information is made available external to the flexible cross-connect system 10 by using SMCs 502 and 552, operating as a Universal Asynchronous Receiver/Transmitter (UART), to provide the status/debug information over a port. In a preferred embodiment, the ports are 19.2 Kb/s serial RJ11 ports.

20 The CP 500 is capable of communicating with the EMS 430 or the NMS 440 over a LAN. The CP 500 interfaces with the LAN via an interface supported by the SCC 506. In a preferred embodiment, the interface is a 10 Mb/s Ethernet (IEEE 802.3) interface.

25 Each processor is capable of communicating with the other processor via an inter-processor link. The SCCs 510 and 558 support ports which provide the inter-processor link between the CP 500 and the DCCP 550. The link allows the processors to communicate provisioning, status and alarms between themselves. In a preferred embodiment, the link is a serial communications 35 link and the ports support communications at 1-2 Mb/s.

The DCCP 550 is provided with an interface, supported by the SCC 560, for modem dial out in the event the LAN interface is

5 unavailable. In a preferred embodiment, the interface is a 9 pin serial interface supporting communications at 19.2 Kb/s.

The DCCP 550 has a management interface that supports up to 10 Data Communications Channels (DCCs), of up to 192 Kb/s, to other flexible cross-connect systems 10. This management 10 interface is supported by the SCC 556. In a preferred embodiment, this interface operates as a multi-channel protocol, such as QMC.

The CP 500 is provided with an interface, supported by the SMC 504, for supporting a TL-1 Bellcore standard interface. In a 15 preferred embodiment, the interface is a 9 pin ASCII over serial interface supporting communications at 19.2 Kb/s.

The DCCP 550 is provided with an interface, supported by the SCC 554, for connecting the flexible cross-connect system 10 to any subtending shelves feeding the main shelf. In a preferred embodiment, the interface is a 10 Mb/s Ethernet (IEEE 802.3) interface.

The CP 500 is provided with an interface, supported by the SCC 512 for inter-card message communications. In a preferred embodiment, the interface is a 4 Mb/s SCL and the inter-card communications path utilizes the 64 byte cell-bus component of the SCL.

While the illustrated embodiment includes two processors with one acting as the master and one as the slave, it is well within the scope of the current invention to have all the 30 software 400 on one processor.

Fig. 6 illustrates the software supporting each of the interfaces described with respect to Fig. 5. In the embodiment illustrated, the CP 500 utilizes a Transmission Control Protocol (TCP)/IP stack 600 to communicate between the software modules on 35 the CP 500 and the management LAN via the management LAN interface (SCC driver 506). As illustrated, a EMS-NE interface module 602, a craft driver 604, a remote monitoring module 606, a

5 control software module 608, and an inter-card messaging module
610 communicate with each other utilizing the TCP/IP stack 600.
The craft driver 604 supports the SMC driver 504 for the craft
interface port, the remote monitoring module 606 supports the SMC
driver 502 for the debug port, and the inter-card messaging
10 module 610 supports the SCC driver 510 for the inter-card
communications port and the SCC driver 512 for the SCL port.

The DCCP 550 includes a TCP/IP Stack 650 on top of a router
652 for communicating between the software modules on the DCCP
550, subtending shelves feeding the main shelf via the packet
15 shelf LAN interface (SCC driver 554), and other flexible cross-
connect systems 10 via the DCC port (SCC driver 556). As
illustrated, a modem driver 654, a remote monitoring module 656,
a control software module 658, and an inter-card messaging module
660 communicate with each other utilizing the TCP/IP stack 650.
The modem driver 654 supports the SCC driver 560 for the modem
interface port, the remote monitoring module 656 supports the SMC
driver 552 for the debug port, and the inter-card messaging
module 660 supports the SCC driver 558 for the inter-card
interface port.

The interconnections described in Figs 5 and 6 allow the
flexible cross-connect system 10 to be connected to multiple
networks at one time. In a preferred embodiment, the flexible
cross-connect system 10 allows for up to 10 DCC connections, 2
LAN connections and 1 modem connection. Thus, the flexible
30 cross-connect system 10 could be part of 13 sub-networks at one
time. In a preferred embodiment, a routing protocol, such as RIP
or Open Shortest Path First (OSPF), is utilized which allows the
connections to be unnumbered so that a single IP address can be
used to identify the flexible cross-connect system 10 for each of
35 the networks that it is connected to. The single IP address
would be the address for the management LAN.

5 Fig. 7 illustrates a sample view of the flexible cross-connect system 10 within multiple networks. In this figure, a flexible cross-connect system 10 (identified as NE1) is part of a network ring consisting of NE1-NE4. Thus, two, of the ten DCC connections are used to have NE1 be part of this network ring.

10 The NE1 is also connected to a rack LAN via the packet shelf LAN interface port (SCC 554), a management LAN via the management LAN interface port (SCC 506), and a modem via the modem port (SCC 560). Each of the PPP connections will not have a unique IP address, instead the single IP address for each sub-network the

15 NE1 is part of is the IP address for the NE1 to management LAN connection.

FIG. 8 illustrates the software architecture, according to one embodiment. The software may be written in an object oriented language such as JAVA, C or C++. In a preferred embodiment, the software is written using C and C++ programming languages, which are running together on one operating system, such as VxWorks® real time operating system sold by Wind River Systems Corporation. In a preferred embodiment, the low-level software which communicates between boards in the system (the CS 420) is written in C, while the interface software which communicates with the EMS 430 or the NMS 440 (the NMIS 410) is written in C++ and Java. In a preferred embodiment, the software runs on the CP 500 and the DCCP 550.

The software architecture includes a Network Management Interface module (NMI) 800, a Provisioning Manager module (PM) 810, an Equipment and Link State Manager module (ELSM) 820, and Inter-Card Communications module (ICC) 830, a Database Manager module (DM) 840, an Alarm Filtering and Reporting module (AFR) 850, a Bi-directional Line Switched Rings (BLSR) Connection Map Manager module (BCMM) 860, a Synchronization Manager module (SM) 870, an Embedded De-bugger module (ED) 875, a SW Program Manager

5 module (SPM) 880, an Inter-Node Communications module (INC) 890, and a Switching Agent module (SA) 895.

The NMI 800 serves as the interface to the EMS 430 and the NMS 440. In a preferred embodiment, the NMI 800 is realized in the C++ programming language, and allows the use of any browser
10 in a network element running a TCP/IP stack to address the system
10.

The PM 810 is responsible for managing a provisioning database for the entire flexible cross-connect system 10. The PM 810 interfaces with subordinate cards via the ELSM 820 and to the management software via the NMI 800. The PM 810 interfaces with a persistent database 842 via the DM 840. The PM 810 retrieves data, including equipment and service data, from the persistent database 842 after a TCC 300 restart and transmits the data to the MS and the subordinate cards. The PM 810 receives provisioning updates from the MS, stores the updates in RAM and the persistent database 842, and notifies the affected cards of the provisioning updates. When a subordinate card requests provisioning data, the PM 810 retrieves the relevant provisioning information from the database 842 and transmits it to the requesting card. In an embodiment that includes a redundant TCC 300, the PM 810 periodically updates the database 842 on the redundant TCC 300. The PM 810 provides an interface to the MS for backing up and restoring the database to an external system.

The ELSM 820 is the central point of communications between the TCC 300 and all other subordinate cards. The ELSM 820 monitors and maintains information about the state of each slot, card, and communications link in the system 10. It notifies other components of the TCC when a subordinate card needs service. It blocks information from being sent to a subordinate card if the subordinate card is in the wrong state. For example, the ELSM 820 would prevent a provisioning update message from being sent to a subordinate card that is in the process of

5 updating its SW. The ELSM 820 communicates with the interface cards via the ICC 830. In a preferred embodiment, the ELSM 820 acts as the single authority on the state of each component in the system. The ELSM 820 on each non facility protected card is responsible for initiating an equipment protection switch when a
10 partial or full failure is detected on a card. In a preferred embodiment, a card presence/alive message is transmitted over an SCL 352 from a non facility protected card to peer cards, subordinate cards, the TCC, and the XC 120. The ELSM 820 is responsible for monitoring this link and initiating the proper
15 action when a failure is detected.

The ICC 830 is responsible for communicating with the subordinate cards. It receives signals from each of the subordinate cards and determines which of the other subordinate cards the signal is being transmitted to based on a routing byte within the cell. It maintains a priority queue, and preferably a high priority queue and a low priority queue, for each subordinate card. It detects and discards corrupt signals received from the subordinate cards.

The AFR 850 performs alarm filtering for the TCC 300 and the system 10. That is, when the arrival or removal of a failure condition is detected, the AFR 850 confirms that the condition has persisted for the requisite period of time, and filters out those that do not persist for the requisite time. The PM 810 is responsible for determining the appropriate filter times and
30 providing them to the AFR 850. Once the arrival or removal of the failure condition clears the appropriate filter, the AFR 850 reports the change in alarm condition to the management system (EMS 430 or NMS 440). The interface cards and the XC 120 also perform failure filtering so that errors are not reported to the
35 TCC 300 until the failure (or removal of the failure) has existed for a predetermined amount of time.

5 The BCMM 860 maintains information related to ring configurations for each node in the entire network. Each node needs to know its identification within the network ring so that it can determine when switch requests are directed to it and when they should be passed along to another node. When a ring
10 configuration is modified, switched to or from a protection channel, at one node of the entire network, the BCMM 860 notifies all of the other nodes of the entire network. In a preferred embodiment, the BCMM utilizes the K1/K2 bytes of the SONET line overhead to transmit this data as well as TCP/IP messages over
15 the DCC.

The SM 870 supports several timing-related services including configuring and monitoring an internal stratum 3 clock reference, provisioning and monitoring of a Building Integrated Timing Supply (BITS) input, provisioning and control of the DSX-1 formatted BITS output, and selection of the timing reference for the system. In addition, the SM 870 selects the timing reference for the BITS output, processes and acts upon synchronization status messages, and controls synchronization switching on synchronization reference changes.

The ED 875 provides the ability to analyze software behavior.

The SPM 880 manages software tracking, downloading and upgrading. That is, the SPM 880 keeps track of the SW versions that are utilized by each of the cards within the system 10, and
30 ensures the SW versions are either upgraded or replaced by new versions when appropriate. For example, when the flexible cross-connect system 10 receives a software upgrade, the SPM 880 establishes communications with the NMI 800 so that a SW load can be received. The SPM 880 then validates the integrity of the SW
35 load and stores the load in a non-volatile file system. The SPM 880 then ensures that the subordinate cards have access to the new software when they boot. Moreover, the SPM 880 can update

5 the boot code and drivers for the system 10 and each subordinate card when necessary. The SPM 880 stores the SW, whether it be the original or a downloaded version, in a SW database 882.

The INC 890 supports communications between the system and other nodes, using both TCP/IP and OSPF protocols.

10 The SA 895 controls the switching of cards (interface, XC 120, 125, or TCC 300, 305) or connections (PPPs 150, SCLs 352, or communication bus 360) within the system 10 from redundant to active when there is a failure in the active one. Thus, the system can autonomously recover from failures.

15 The present system can be utilized in a variety of configurations supporting transport of data on MAN/LAN, interLATA and interexchange networks. Because the system can establish cross connections between any interface cards and can use a data plane for local switching, a wide variety of transport configurations can be supported, including configurations in which a virtual LAN is created in the data plane 110, and access to the telecom plane 100 is granted for transport to other nodes.

20
25 Although this invention has been illustrated by reference to specific embodiments, it will be apparent to those skilled in the art that various changes and modifications may be made, which clearly fall within the scope of the invention. The invention is intended to be protected broadly within the spirit and scope of the appended claims.